# Mach 1 Linear Algebra and Analytic Greandery

Instructor: dr Adam Abrams

## Monday 9 October 2023



# Vectors and matrices Vector operations Lines and planes Linear independence Matrix operations Systems of linear equations



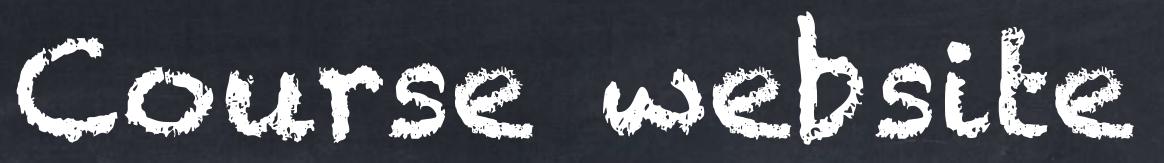
# Complex numbers and polynomials Rectangular and polar forms Complex conjugate Zeros of polynomials Factoring and remainders



# All course policies can be found at http://theadamabrams.com/1433

the semester.

Grades will be recorded on ePortal: http://eportal.pwr.edu.pl/



## Lecture slides and problem sets will also be posted to this site throughout

The same grade is used for 1433W and 1433C. Six quizzes (5 points each), but the lowest score is ignored! Two exams (15 points each). Participation (5 points).

This makes  $5 \times 5 + 15 + 15 + 5 = 60$  total possible points.

Points	[0, 30)	[30, 36)	[36, 42)	[42, 48)	[48, 54)	[54, 60]
Grade	2.0	3.0	3.5	4.0	4.5	5.0

This might change. If so, there will be an announcement.





## The same grade is used for 1433W and 1433C.

Points	[0, 30)	[30, 36)	[36, 42)	[42, 48)	[48, 54)	[54, 60]
Grade	2.0	3.0	3.5	4.0	4.5	5.0

More than 3 unexcused absences after 13 Oct  $\rightarrow$  course grade 2.0. You can work together on task lists (which are not graded), but quizzes and exams are individual. All work can be checked in one-on-one meeting. Cheating on quizzes  $\rightarrow$  quiz grade 0. 0

- Cheating on exams  $\rightarrow$  course grade 2.0. 0



# Accessibility and Support Department for People with Disabilities Office: building C-13 room 109 Website: https://ddo.pwr.edu.pl/ Email: pomoc.n@pwr.edu.pl

If you need extra time on exams, course materials in a different format, or other **accommodations**, please talk to me!





# poles

English Language and some polls



# Poles

# polls

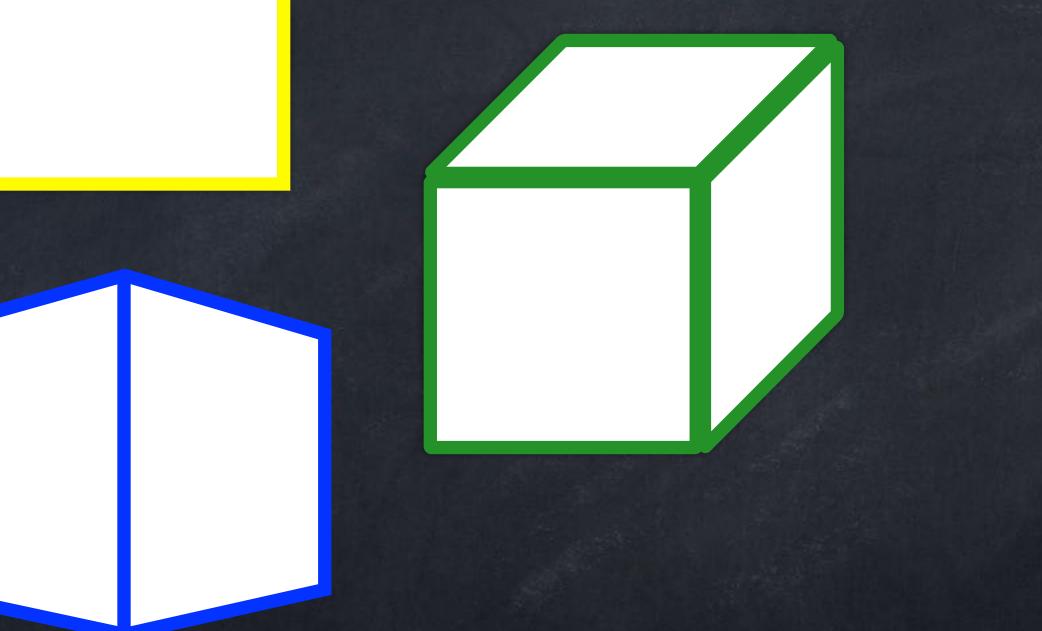




## These are all correct!

all thinking of the same thing.





If multiple people draw or talk about a cube, we need to be sure we are



The word "vector" can mean many things. At times we will think of a **vector** as

- a list.
- a point (that is, a location in 2D plane or 3D space). 0
- an arrow starting at the origin.
- an arrow starting anywhere.

There is another option:

an element of an abstract vector space, but we won't use that idea of a vector in this class.





# A vector is a list of numbers. We can write the same list of numbers in many formats. For example,

(5,3,8) (5,3,8) [538]

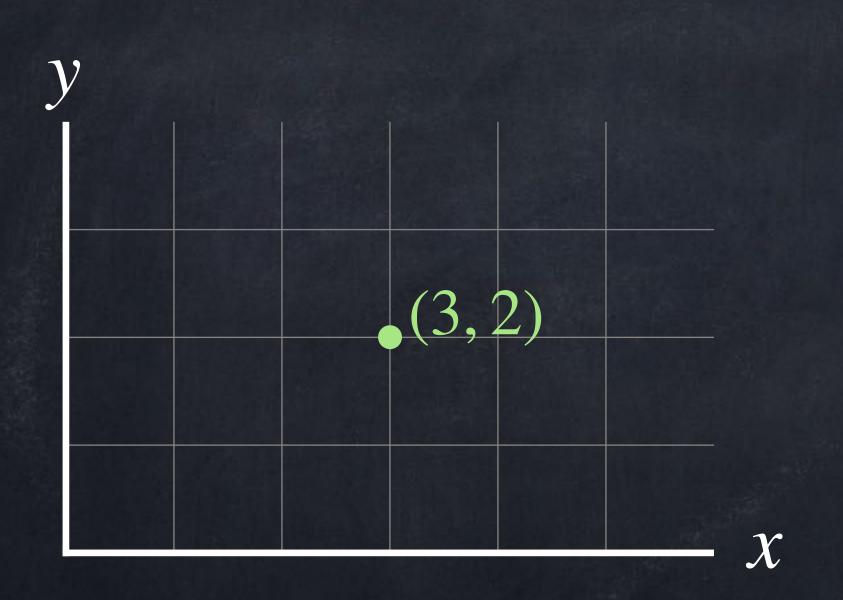
are all exactly the same vector. Each numbers is a component of the vector. • For [5,3,8], the "1<sup>st</sup> component" is 5, the "2<sup>nd</sup> component" is 3, etc. • We often label the components with subscripts:  $\vec{u} = \langle u_1, u_2, u_3 \rangle$ . But sometimes we instead label a whole vector this way:  $\vec{u_1}$  and  $\vec{u_2}$ .



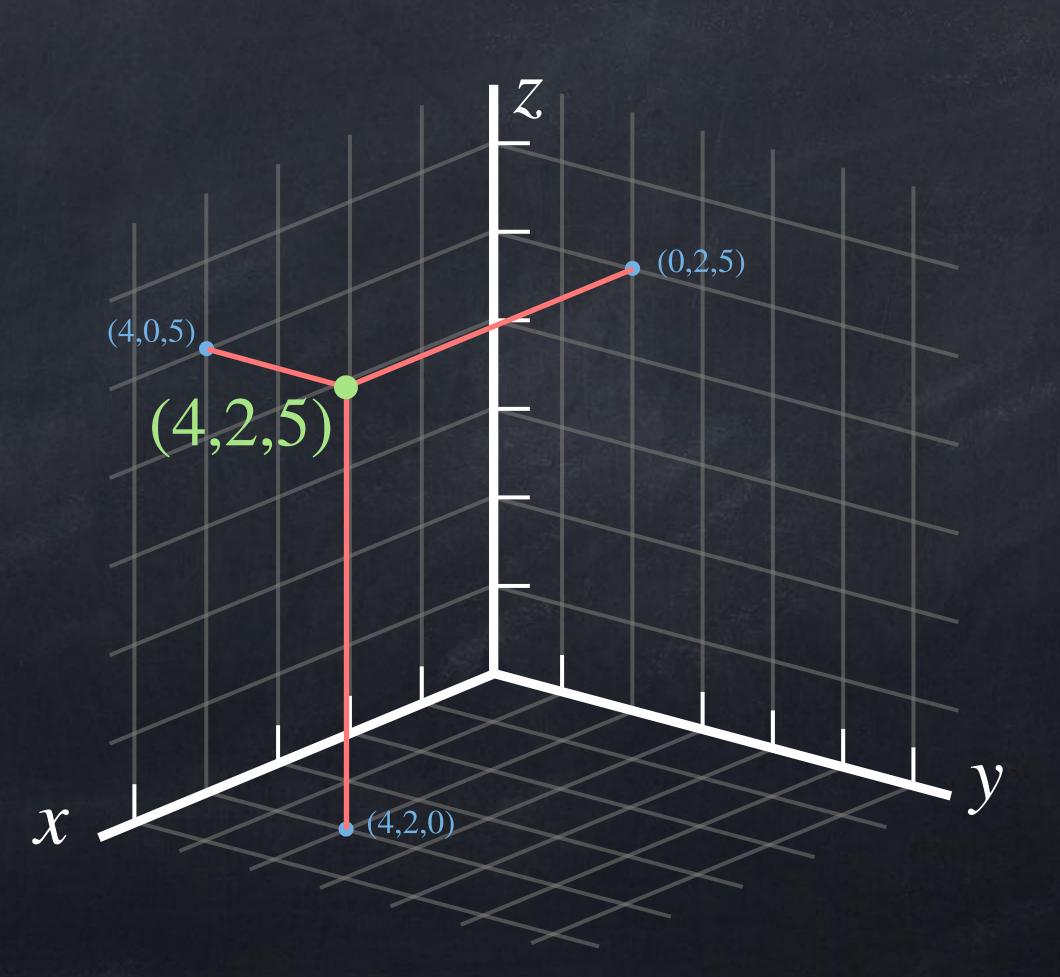
 $\begin{bmatrix} 5 \\ 3 \\ 8 \end{bmatrix}$   $\begin{bmatrix} 5 \\ 3 \\ 8 \end{bmatrix}$ 



## A vector is a point in 2D or 3D space.

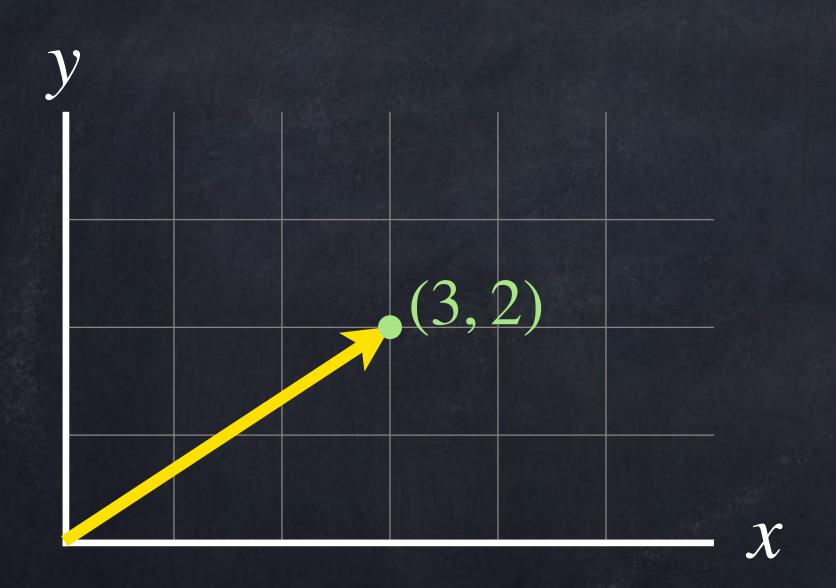




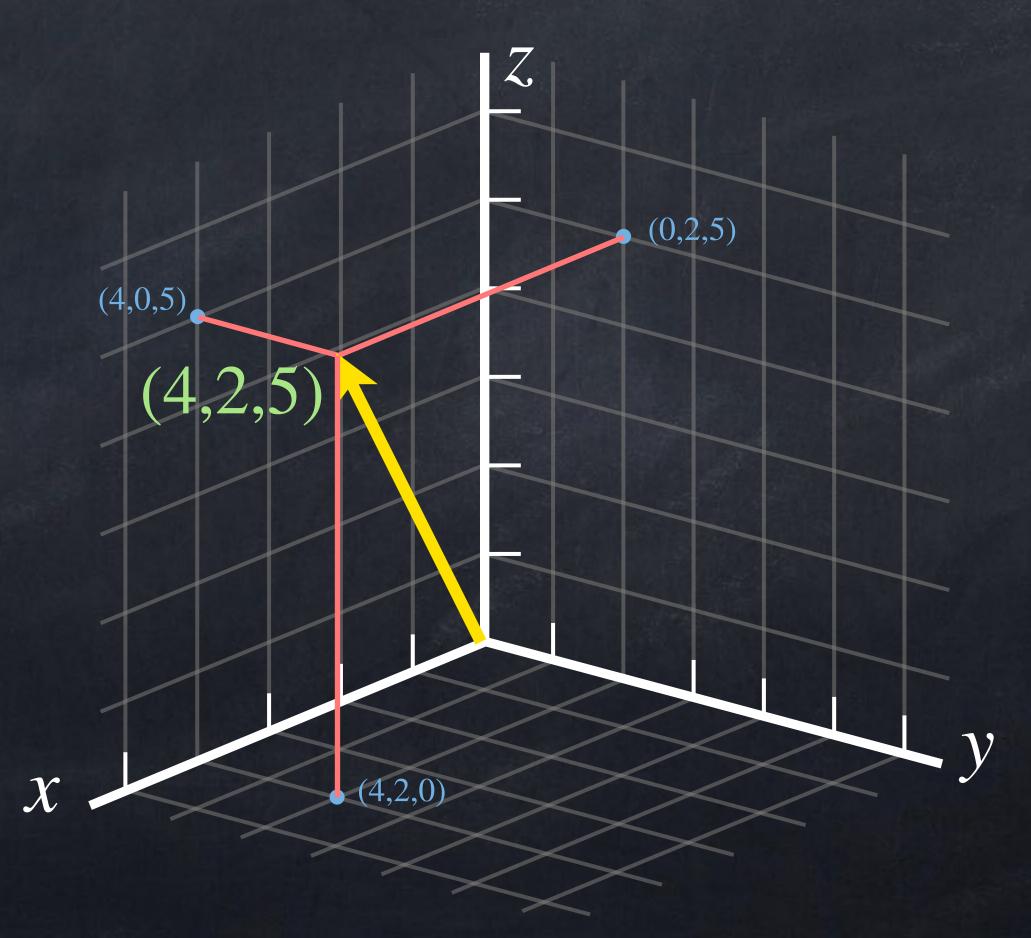




## A vector is something that has a magnitude and a direction. In other words, it is an arrow.





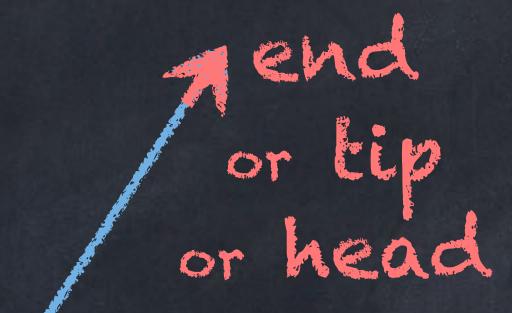




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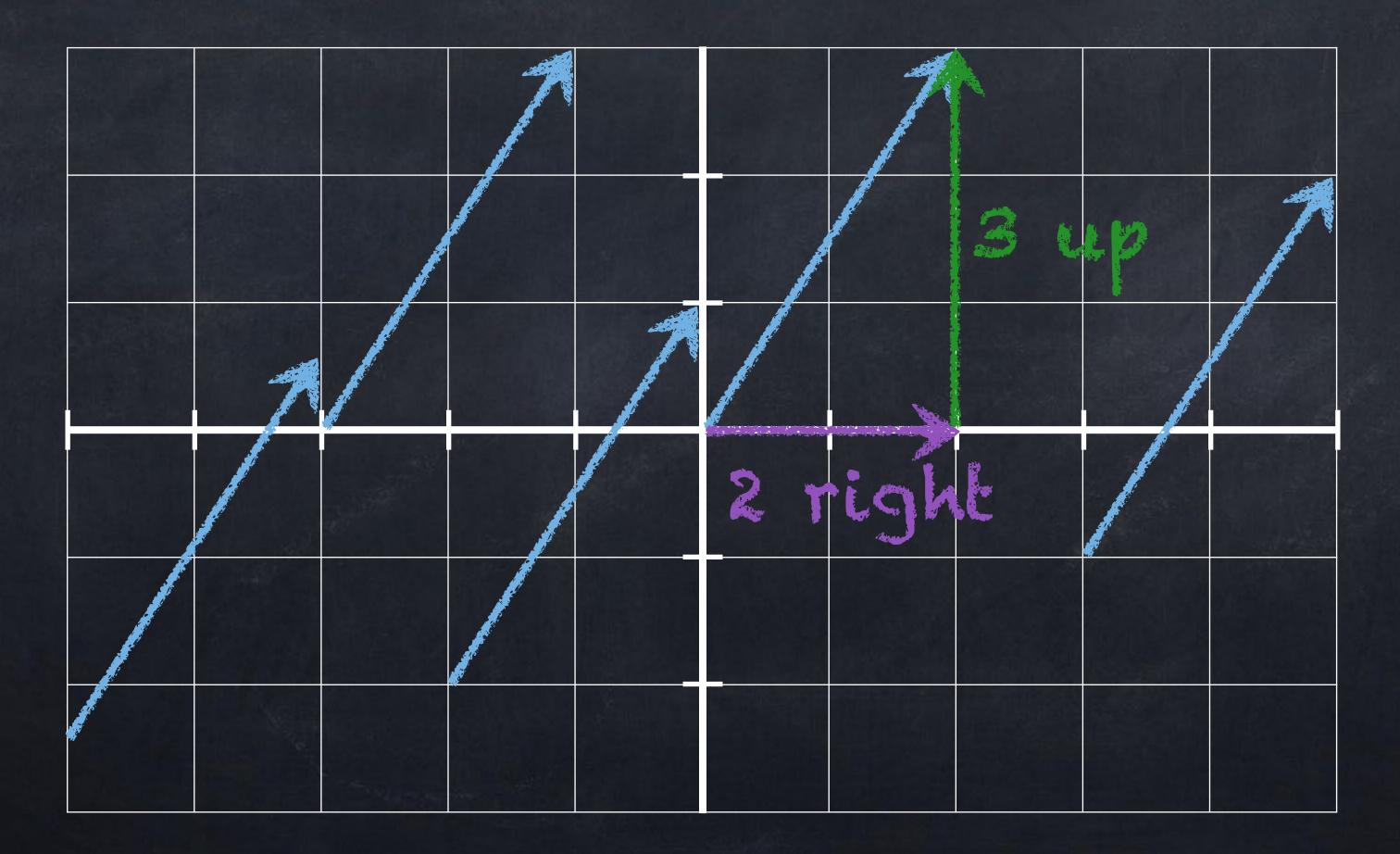




or lail



## A vector is something that has a magnitude and a direction. In other words, it is an arrow.

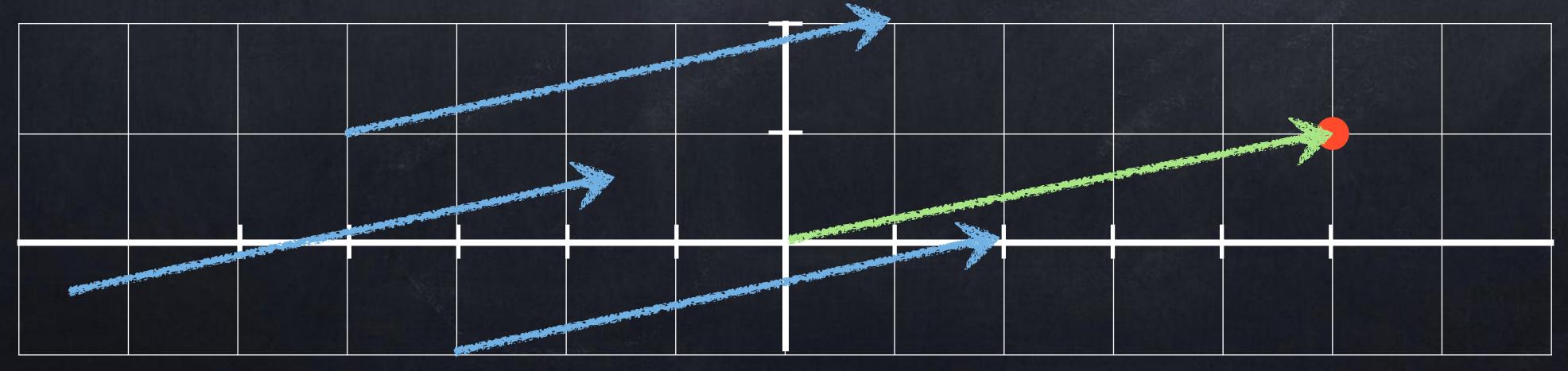






# VECTS QS Points

- A vector is something that has a magnitude and a direction. In other words, it is an arrow.
- **Depending on context**, a vector like (5,1) might refer to
- any arrow that points in a direction 5 right and 1 up, or 0
- the specific arrow from (0,0) to (5,1), or
- the point (5,1).

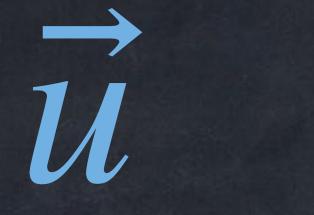


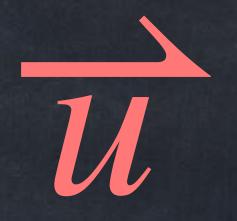


# TOWS

Lists







Often we use letters u, v, w or a, b, c for vectors. meaning.

In physics,  $\overrightarrow{F}$  for force.

• The zero vector is  $\vec{0} = \langle 0, 0 \rangle$  in 2D and  $\vec{0} = \langle 0, 0, 0 \rangle$  in 3D.

# Veeler varia dies

In different text/videos, a vector variable might be written as any of these:



# If the vector has a specific meaning, we might use a letter related to that

their second components are equal, and so on). • Example:  $\langle 5, 1, 9 \rangle = \langle 2+3, \frac{6}{6}, 13-4 \rangle$ 

•  $\vec{u} = \langle 1, -3 \rangle$  $\circ$   $\vec{u} = 5$ 

Two vectors are equal if they have the same size and the components of the two vectors are equal (that is, their first components are equal, and

As with numbers, sometimes an equation describes one specific value

a x = -8

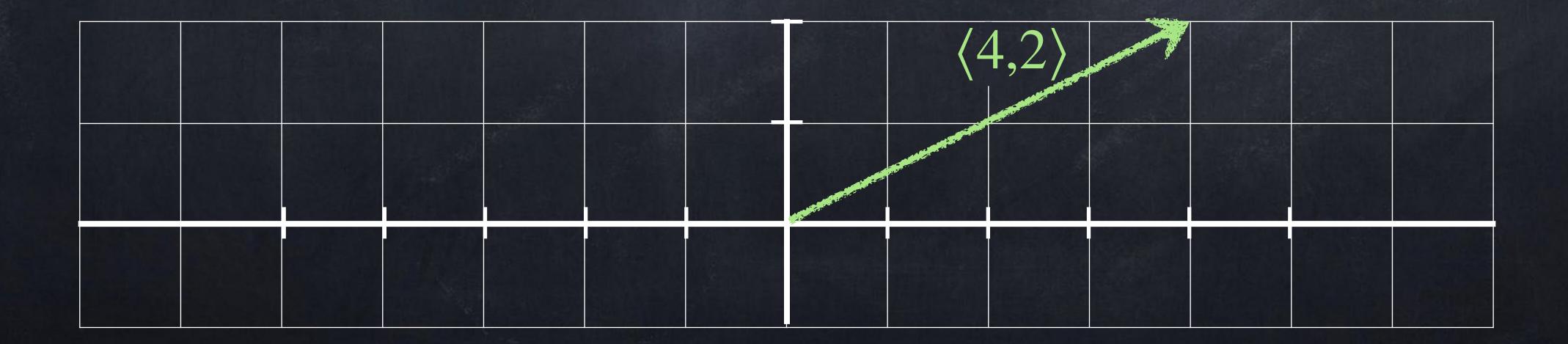
and sometimes there are many values that make an equation true:

 $x^2 - 4x + 3 = 0$ 



# $\vec{v} = \sqrt{v_1^2}$

In 2D or 3D, this is exactly the physical length of the arrow, or the length of the line segment from the origin to the point  $\vec{v}$ .



# MACCOMMENTER

The magnitude (or length or norm) of the vector  $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$  is

$$2 + v_2^2 + \dots + v_n^2$$
.



# $\vec{v} = \sqrt{v_1^2} +$

In 2D or 3D, this is exactly the physical length of the arrow, or the length of the line segment from the origin to the point  $\vec{v}$ .

Example: for  $\vec{v} = \begin{vmatrix} 4 \\ 2 \end{vmatrix}$  we have  $\vec{v} = \sqrt{20} = 2\sqrt{5}$  because

side  $\langle 4,2 \rangle$ Length  $\sqrt{20}$ 

# Machellerde

The magnitude (or length or norm) of the vector  $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$  is

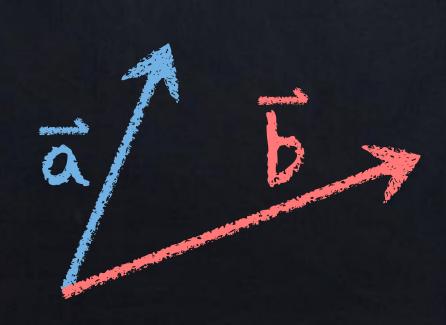
$$2 + v_2^2 + \dots + v_n^2$$
.

side Length 4



# As lists, vectors are added by adding each coordinate. • Example: $\langle 9, -4 \rangle + \langle 5, 6 \rangle = \langle 14, 2 \rangle$ • Example: $\begin{bmatrix} 5 \\ 8 \end{bmatrix} + \begin{bmatrix} -2 \\ 7 \end{bmatrix} = \begin{bmatrix} 3 \\ 15 \end{bmatrix}$

As arrows, add vectors "tip-to-tail" (also called "parallelogram method").



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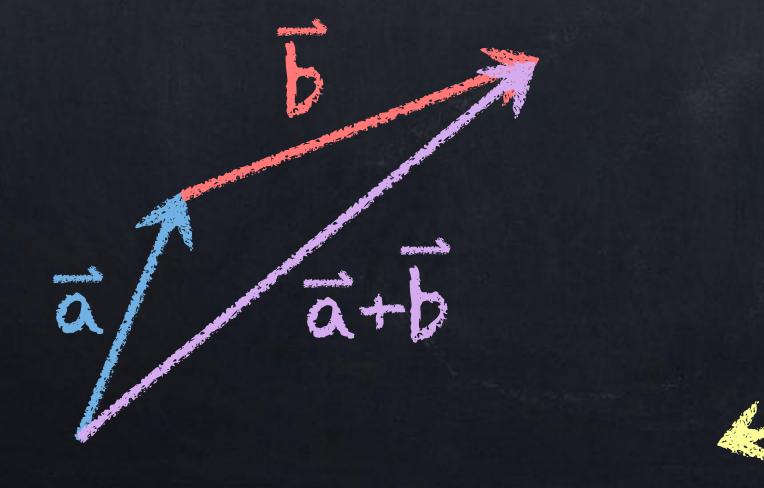
## As arrows, add vectors "tip-to-tail" (also called "parallelogram method").

atb



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As arrows, add vectors "tip-to-tail".





# What does $5 \times 3$ mean?

• More advanced: no pictures, just 5 + 5 + 5.

What does  $5 \times \frac{1}{3}$  mean?

Depending on the context, multiplication can have 0 different meanings or interpretations. This is also true for subtraction, and really for almost anything in math.

MULLEPLECALLOIA



# $5 \times 9.2$ ? $7.65 \times (-12)$ ?

# What is $\begin{vmatrix} 8 \\ -3 \end{vmatrix} + \begin{vmatrix} 8 \\ -3 \end{vmatrix}$ ?

We can also write this as  $2 \begin{bmatrix} 8 \\ -3 \end{bmatrix}$ .

# In general, $2\vec{a} = \vec{a} + \vec{a}$ , and $3\vec{a} = \vec{a} + 2\vec{a}$ , etc. What about $2.5 \vec{a}$ or $\sqrt{3\vec{a}}$ ?

For this class, a scalar is a real number. Given a scalar s and a vector  $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$ , we can multiply s and  $\vec{v}$  to get

 $\vec{sv} = \langle sv_1, sv_2, \dots, sv_n \rangle.$ 

## Examples:

- $3\langle 8,1\rangle = \langle 24,3\rangle$ •  $\frac{1}{2}\langle 8,1\rangle = \langle 4,\frac{1}{2}\rangle$
- $4\langle -3, 9.1 \rangle = \langle -12, 36.8 \rangle$
- $-2\langle 5, -4 \rangle = \langle -10, 8 \rangle$
- $0\langle 5,7\rangle = \langle 0,0\rangle$

Scalar multiplication

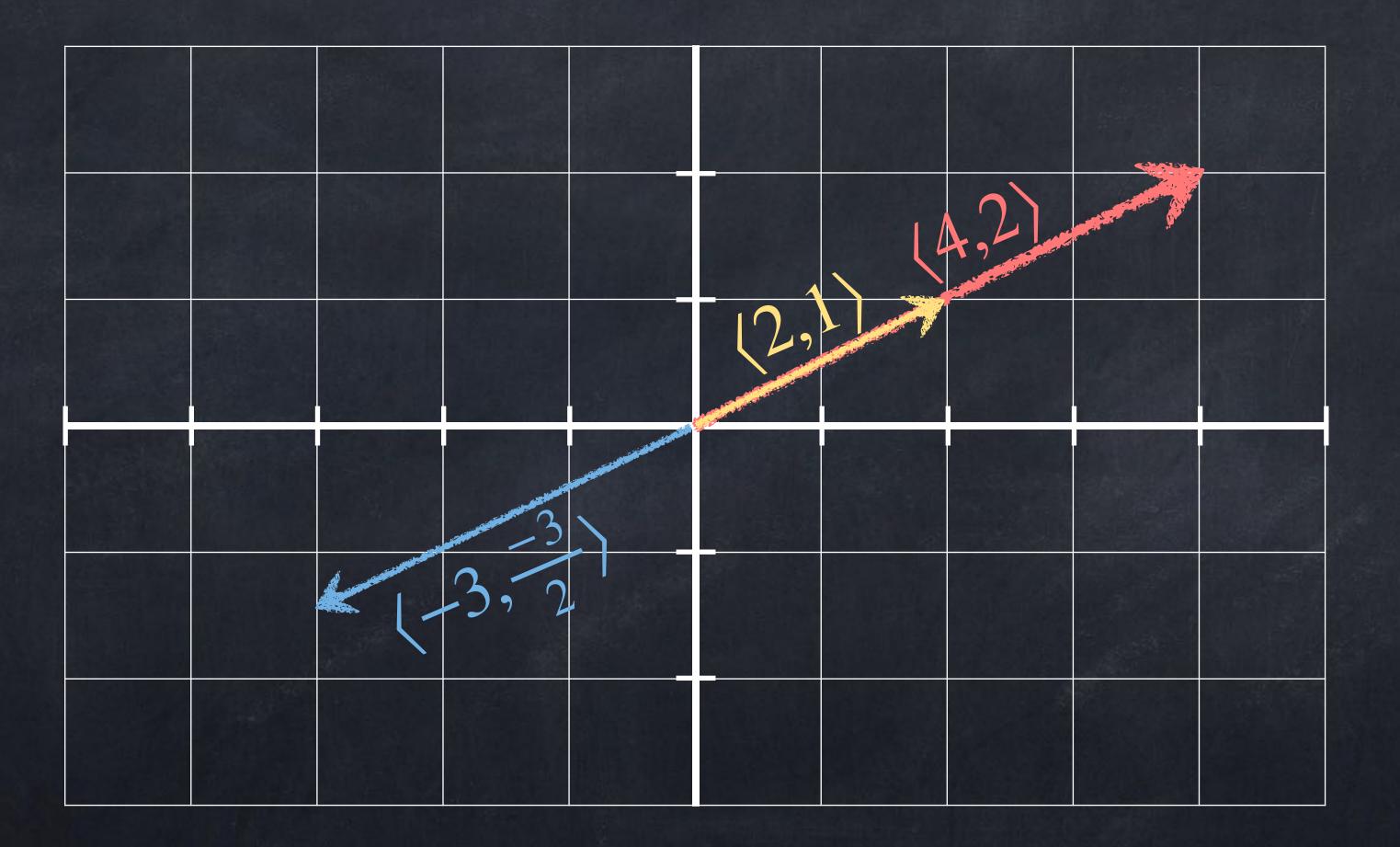
such that  $\vec{a} = s \vec{b}$ .

### Examples:

•  $\langle 24, 3 \rangle$  is a scalar multiple of  $\langle 8, 1 \rangle$  (we can use s = 3). •  $\langle 4, 0.5 \rangle$  is a scalar multiple of  $\langle 8, 1 \rangle$  (we can use s = 0.5).  $\checkmark$   $\langle 24, 10 \rangle$  is *not* a scalar multiple of  $\langle 8, 1 \rangle$ .

We say that  $\vec{a}$  is a scalar multiple of  $\vec{b}$  if there is some number (scalar) s

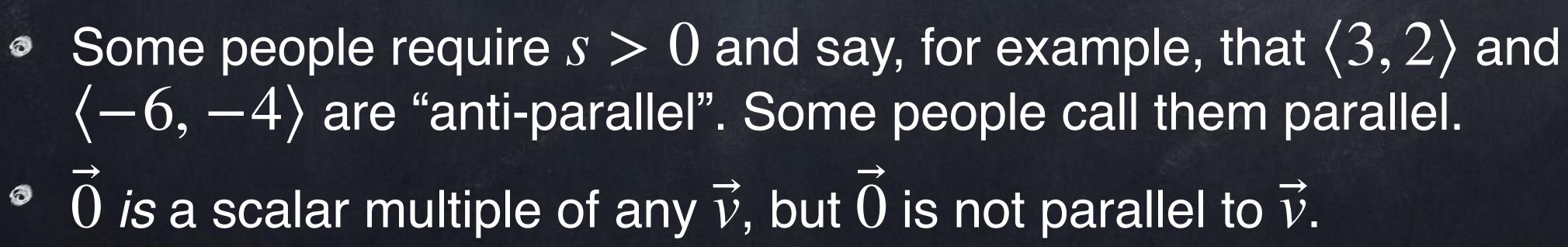
# Geometrically, $\vec{sv}$ is a "stretched" version of $\vec{v}$ .



# Two vectors $\vec{u}$ and $\vec{v}$ are parallel if $\vec{u} = s\vec{v}$ for some $s \neq 0$ .

 $\langle -6, -4 \rangle$  are "anti-parallel". Some people call them parallel.  $\vec{0}$  is a scalar multiple of any  $\vec{v}$ , but  $\vec{0}$  is not parallel to  $\vec{v}$ .

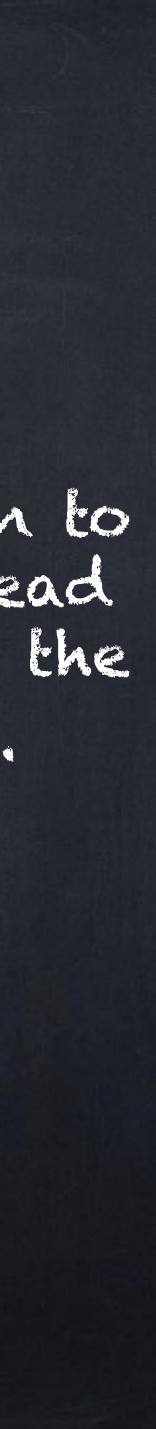




Later, we will talk about the general idea of a "basis", but for now we will use just one 2D example and one 3D example. In 2D, the standard basis vectors are Il's also common to  $\vec{i} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\vec{j} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . write "hats" instead of arrows above the letters:  $\hat{i}, \hat{j}, \hat{k}$ . In 3D, the standard basis vectors are 0  $\vec{i} = \begin{vmatrix} 1 \\ 0 \end{vmatrix}$  and  $\vec{j} = \begin{vmatrix} 0 \\ 1 \\ 0 \end{vmatrix}$  and  $\vec{k} = \begin{vmatrix} 0 \\ 0 \end{vmatrix}$ . We can write any vector using scalar multiples, these basis vectors,

and vector addition.

# BASES VEEDTS





We can write any vector using scalar multiples, these basis vectors, and vector addition.

Examples:  $\begin{bmatrix} 5 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 2 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 5\vec{i} + 2\vec{j}$  $\begin{bmatrix} 6\\0.91\\-2 \end{bmatrix} = 6\vec{\imath} + 0.91\vec{\jmath} - 2\vec{k} \qquad \circ \begin{bmatrix} a\\b \end{bmatrix} = a\vec{\imath} + b\vec{\jmath}$  $= 4\vec{\imath} + \vec{k}$ 0



# $\begin{array}{c} 5 \\ 2 \\ \end{array} = 5\vec{\imath} + 2\vec{j} \end{array}$



We can subtract vectors using coordinates. • Example:  $\langle 9, -4 \rangle - \langle 5, 6 \rangle = \langle 4, -10 \rangle$ • Example:  $\begin{bmatrix} 5 \\ 8 \end{bmatrix} - \begin{bmatrix} -2 \\ 7 \end{bmatrix} = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$ 

What does  $\vec{u} - \vec{v}$  mean geometrically?

- geometric method of addition ("tip-to-tail") to draw  $\vec{u} + (-\vec{v})$ .
- What does a b mean for numbers?

• We could first find the scalar multiple  $-\vec{v} = (-1)\vec{v}$  and then use the



3

## What does 5 - 3 mean **on a number line**?



## Answer: The number 5 - 3 describes how to move from 3 to 5.

# In general, a - b describes how to move from b to a.



## What does 5 - 3 mean on a number line?



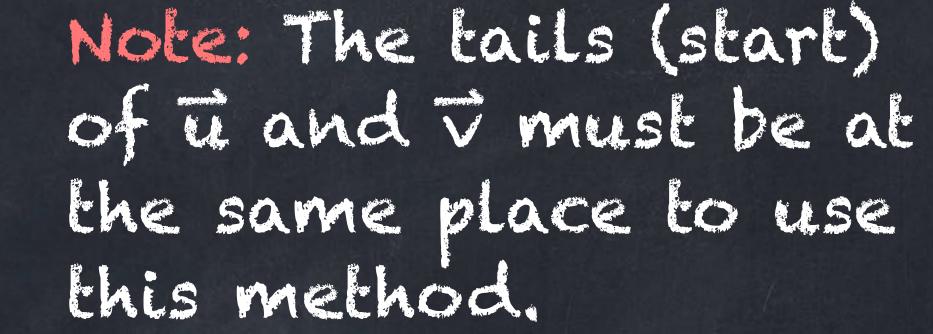
# Answer: The number 5 - 3 describes how to move from 3 to 5. • To go from 5 to 3 instead, we move *left*, which is why 3 - 5 is negative.

In general, a - b describes how to move from b to a.



## The vector $\vec{u} - \vec{v}$ points from the end of $\vec{v}$ to the end of $\vec{u}$ .

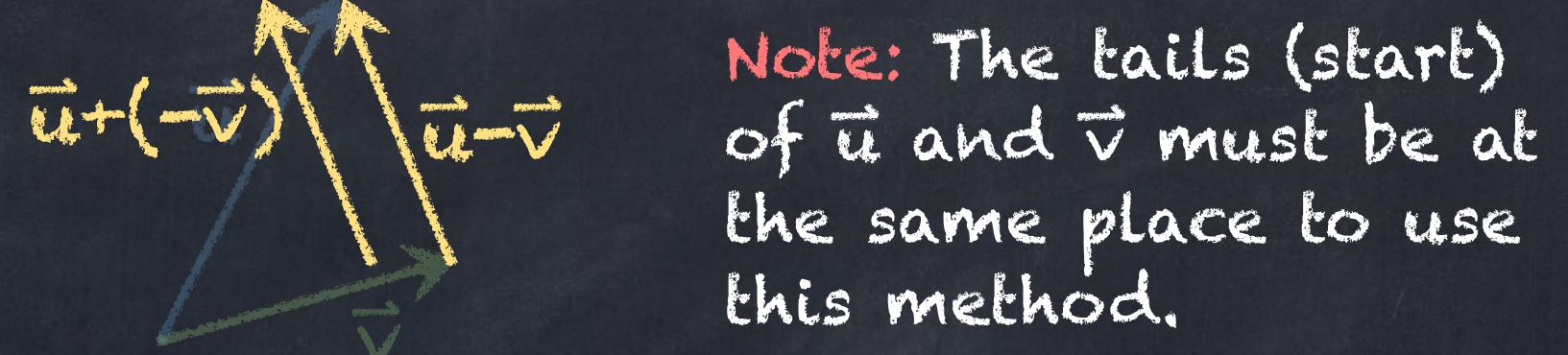
# In general, a - b describes how to move from b to a.







## The vector $\vec{u} - \vec{v}$ points from the end of $\vec{v}$ to the end of $\vec{u}$ .



This agrees with finding  $\vec{u} - \vec{v}$  by adding  $\vec{u} + (-\vec{v})$  tip-to-tail.

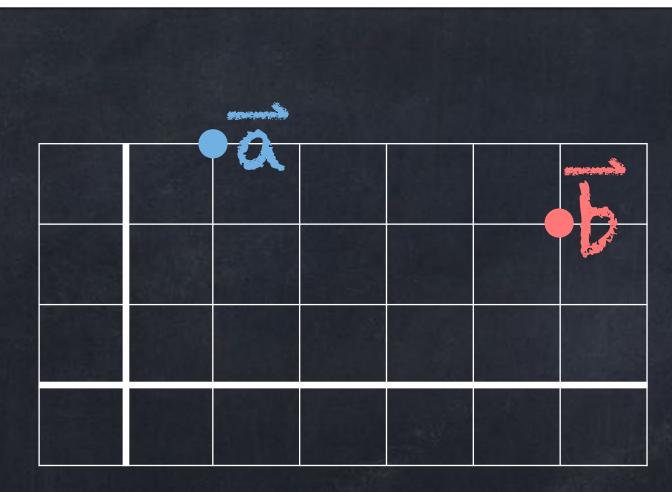


# Vector $\vec{u} - \vec{v}$ points from the end of $\vec{v}$ to the end of $\vec{u}$ .

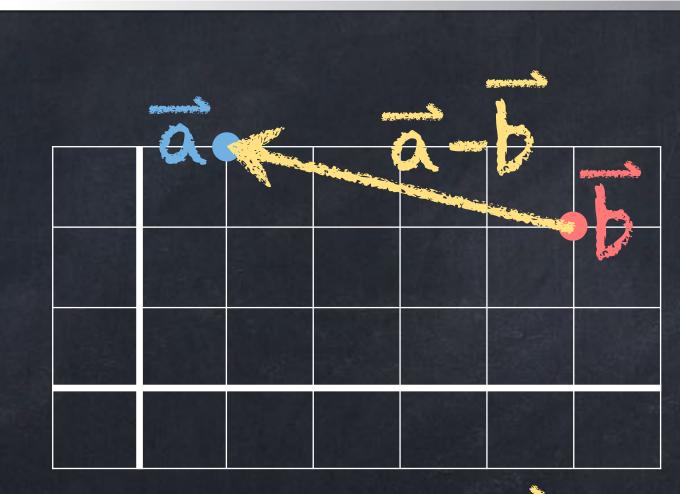
 $\vec{u} = \vec{v}$  Note: The tails (start) of  $\vec{u}$  and  $\vec{v}$  must be at the same place to use this method.

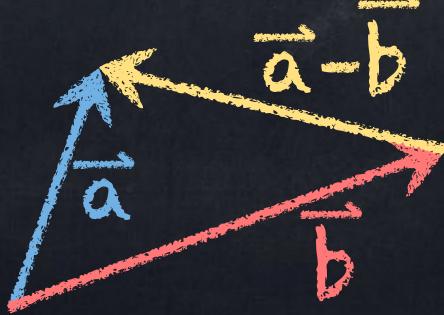


# If we think of $\vec{a}$ and $\vec{b}$ as **points**, then $\vec{a} - \vec{b}$ literally goes from $\vec{b}$ to $\vec{a}$ .







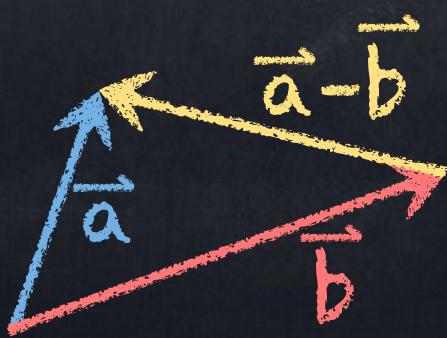




### In terms of arrows, we have "tip-to-tail addition". Example: 0

# • If $\vec{a}, \vec{b}$ start at the same point, then $\vec{a} - \vec{b}$ points from the end of $\vec{b}$ to the end of $\vec{a}$ .

a+b



There are actually many kinds of multiplication involving vectors:

- Scalar multiple  $s \vec{u}$
- Dot product  $\vec{u} \cdot \vec{v}$
- Cross product  $\vec{u} \times \vec{v}$
- Outer product  $\vec{u}^{\top} \vec{v}$  for rows
- Convolution  $\vec{u} * \vec{v}$
- Kronecker product  $\vec{u} \otimes \vec{v}$
- Hadamard product  $\vec{u} \odot \vec{v}$

Never write  $\vec{a}\vec{b}$  without a symbol in between the vectors!



In our class, we'll only use these.

# For fractions, $\frac{1}{2} \cdot \frac{1}{3} = \frac{1 \cdot 1}{2 \cdot 3}$ (easy), but $\frac{1}{2} + \frac{1}{3}$ is $not \frac{1+1}{2+3}$ .

For vectors, it's the opposite:  $\begin{bmatrix}
1 \\
2
\end{bmatrix} + \begin{bmatrix}
1 \\
3
\end{bmatrix} = \begin{bmatrix}
1 + 1 \\
2 + 3
\end{bmatrix} (easy).$   $\begin{bmatrix}
1 \\
2
\end{bmatrix} \cdot \begin{bmatrix}
1 \\
3
\end{bmatrix} is not \begin{bmatrix}
1 \cdot 1 \\
2 \cdot 3
\end{bmatrix}. If you do this calculation on a quiz or exam, you will lose points.$ 



out loud as "A dot B"). It is a number that can be computed as either •  $\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2$ 

Or

•  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\text{angle between } \vec{a} \text{ and } \vec{b}).$ 



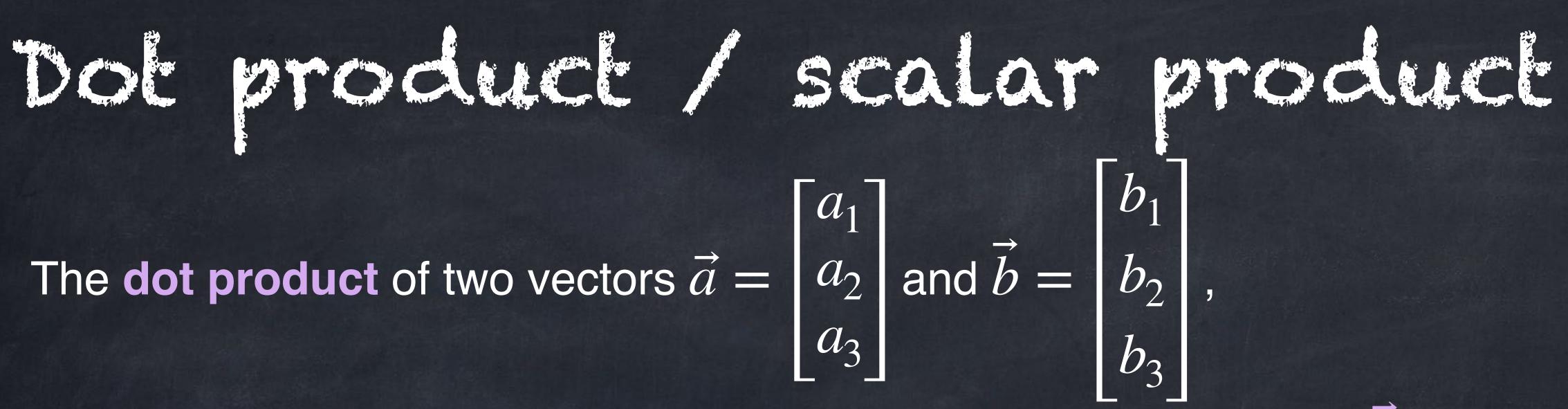
# The **dot product** of two vectors $\vec{a} = \begin{vmatrix} a_1 \\ a_2 \end{vmatrix}$ and $\vec{b} = \begin{vmatrix} b_1 \\ b_2 \end{vmatrix}$ ,

# also called the scalar product or inner product, is written as $\vec{a} \cdot \vec{b}$ (said



out loud as "A dot B"). It is a number that can be computed as either •  $\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$ Or

•  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\text{angle between } \vec{a} \text{ and } \vec{b}).$ 



also called the scalar product or inner product, is written as  $\vec{a} \cdot \vec{b}$  (said



# Officially there is a problem session from 12:15 - 13:00 today. We will discuss the topics mentioned on the survey. 0

and the second	
Algebra	Expand $(2x + 3)(x + 3)$
Lines	Does the point $(3, 5)$ The point $(3, -20)$
Quadratic f.	Solve $x^2 - 2x - 9$
Exponents	Re-write $(2^3)^2 \cdot 2^{10}$
Systems	Solve $\begin{cases} 3x+1 = \\ x-y = \end{cases}$
Trig	What is $\cos(30^\circ)$ ? Find a value of $\theta$ for



- If you can already answer the tasks below, you can skip today's session.

-5).

- 8) lie on the line y = 4 + 8(x 3)? )? The point (3, 4)?
- = 0.
- in the form  $2^{\Box}$ .
- 4 3.

or which  $\sin(\theta) = \frac{1}{\sqrt{2}}$  and  $\cos(\theta) = \frac{-1}{\sqrt{2}}$ .